

## The Application of Parabola of safety for Physics Problem Solving

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**Abstract.** In this article we calculate the parabola safety and its application for some physics problems. Using equation of motion for projectile we find the Parabola of safety. Deriving the parabola of safety here we used zero discriminant of quadratic equation. Inside parabola safety is unsafe region from projectile. The application of the equation is presented for finding maximum distance, minimum speed in some cases of problems.

**Keyword:** Projectile motion; parabola of safety; physics problems

### 1. Introduction

Projectile motion is a combination of horizontal motion with constant velocity and constant acceleration vertical motion. The equation of horizontal motion is called uniform striated motion and vertical motion is called uniformly changing straight motion. The path equation resulting from the combination of the two is a parabolic equation. In this parabolic motion air resistance and the effect of the earth's rotation are ignored. In this article, we will derive the parabola of safety by using algebra approach. The equation is used to solve four example problems.

### 2. Methods

Let us start with basics equation of projectile position as function of time

$$x = v_0 \cos \theta t, \quad y = v_0 \sin \theta t - \frac{1}{2} g t^2 \quad (1)$$

Where  $v_0$  is initial velocity,  $\theta$  is angle initial velocity respect to the horizontal,  $t$  is time and  $g$  is gravitational acceleration. We take the initial position as center of coordinate.

By eliminating time we can get the trajectory equation

$$y = x \tan \theta - \frac{1}{2v_0^2} g x^2 \sec^2 \theta \quad (2)$$

This is parabolic equation as function of position  $x$

### 3. Result and Discussion

Using trigonometry identity  $\sec^2 \theta = 1 + \tan^2 \theta$ . We get quadratics equation in term of  $\tan \theta$ .

$$y = x \tan \theta - \frac{1}{2v_0^2} g x^2 (1 + \tan^2 \theta)$$

$$\frac{g x^2}{2v_0^2} (\tan^2 \theta) - x \tan \theta + y + \frac{g x^2}{2v_0^2} = 0$$

By taking discriminant zero,

$$\tan \theta = \frac{x \pm \sqrt{x^2 - 4 \frac{g x^2}{2v_0^2} \left( y + \frac{g x^2}{2v_0^2} \right)}}{2 \left( \frac{g x^2}{2v_0^2} \right)}$$

We have condition for  $\tan \theta$  is real value

$$x^2 - 4 \frac{g x^2}{2v_0^2} \left( y + \frac{g x^2}{2v_0^2} \right) \geq 0$$

By little algebra we will arrive to the equation

$$y \leq \frac{v_0^2}{2g} - \frac{g}{2v_0^2} x^2 \quad (3)$$

This equation tell us that for given horizontal position  $x$  the vertical position will be less than or equal as given by it.

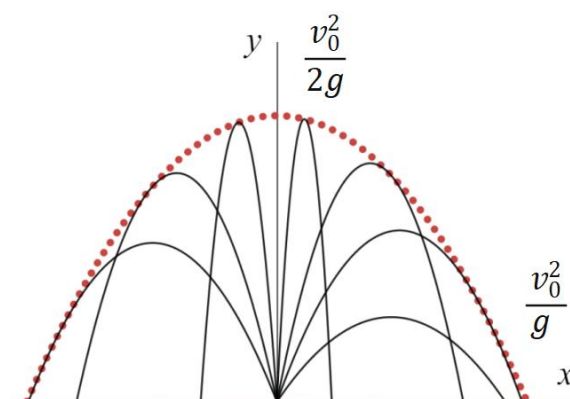


Figure 1. Envelop of parabola of safety

Above equation is critical position which projectile can reach. Outside domain is safe from attack of projectile and inside parabola is unsafe region.

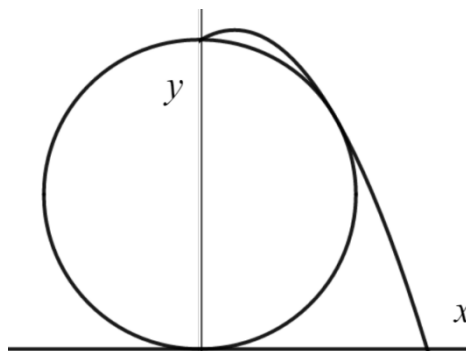


Figure 2. Optimum trajectory of projectile to reach the top of the sphere which is tangent to sphere and tangent to the envelop of parabola of safety

The first example for application is given of sphere of radius  $R$ , we want to find the minimal speed to reach the top from the ground. Let us assume the origin is the on the top sphere and projectile fired from the top having same path and speed if we fired projectile from the ground. In this problem we have circle equation .

$$x^2 + y^2 + 2yR = 0$$

Using the parabola of safety equation by eliminating  $y$ .

$$x^2 + \left(\frac{v_0^2}{2g} - \frac{g}{2v_0^2}x^2\right)^2 + 2\left(\frac{v_0^2}{2g} - \frac{g}{2v_0^2}x^2\right)R = 0$$

The above equation can be simplified become biquadratic equation.

$$\left(\frac{g}{2v_0^2}\right)^2 x^4 + x^2\left(\frac{1}{2} - \frac{gR}{v_0^2}\right) + \frac{v_0^2}{g}\left(\frac{v_0^2}{4g} + R\right) = 0$$

By taking zero discriminant

$$\left(\frac{1}{2} - \frac{gR}{v_0^2}\right)^2 - 4\left(\frac{g}{2v_0^2}\right)^2 \frac{v_0^2}{g}\left(\frac{v_0^2}{4g} + R\right) = 0$$

Finally we get initial velocity of the top sphere

$$v_0 = \sqrt{\frac{gR}{2}}$$

The initial speed from the ground can be derived from conservation of energy

$$v = \sqrt{v_0^2 + 4gR} = 3\sqrt{\frac{gR}{2}}$$

The second example is finding maksimum horizontal distance if projectile fired from a hill heigh  $h$  with inital speed  $v_0$ . We can find maksimum distance by using

$$y = \frac{v_0^2}{2g} - \frac{g}{2v_0^2}x^2 = -h$$

With easy algebra we can find maksimum horizontal distance

$$x_{\max} = \sqrt{\frac{2v_0^2}{g} \left( \frac{v_0^2}{2g} + h \right)}$$

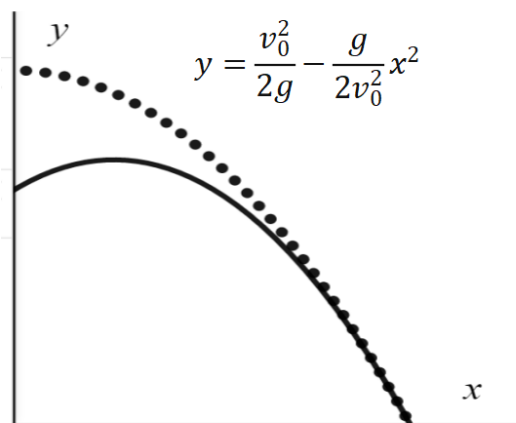


Figure 3. Optimum trajectory of projectile to reach maximum horizontal distance which is tangent to the envelop of parabola of safety

The third example is finding the minimum velocity to reach horizontal distance  $x=d$  and heigh  $y=h$

$$\frac{v_0^2}{2g} - \frac{g}{2v_0^2}d^2 = h$$

We can rewrite in the form

$$\frac{v_0^4}{2} - v_0^2gh - \frac{g^2d^2}{2} = 0$$

Using abc formula for quadratic equation we find minimum initial speed is

$$v_0 = \sqrt{g \left( h + \sqrt{h^2 + d^2} \right)}$$

The last example of the application is finding maksimum distance in the case projectile motion fired in inclined plane. The angle the plane makes with the horizontal,  $\varphi$ . The projectile hits the incline plane at the position  $x = L\cos\varphi$  and  $y = L\sin\varphi$ , where  $L$  is distance along the incline plane.

$$L\sin\varphi = \frac{v_0^2}{2g} - \frac{g}{2v_0^2}L^2\cos^2\varphi$$

By rearranging the equation we can the quadratic equation in term of  $L$

$$\frac{g}{2v_0^2}L^2\cos^2\varphi + L\sin\varphi - \frac{v_0^2}{2g} = 0$$

Again using abc formula for quadratic equation we can easily get the distance

$$L = \frac{v_0^2}{g(1 + \sin\varphi)}$$

#### 4. Conclusion

We have derived the equation of Parabola of Safety by taking zero discriminant in the quadratic equation in terms of  $\tan \theta$ . The region outside envelop is safe from projectile. We have given some examples of its application for finding optimum distance or minimum initial velocity.

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